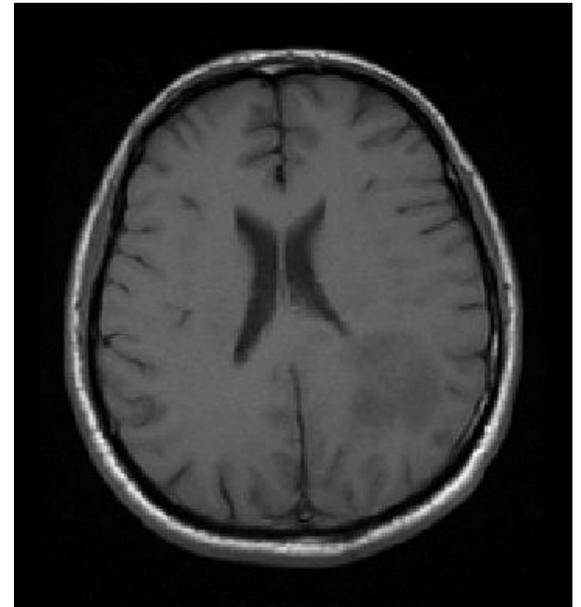
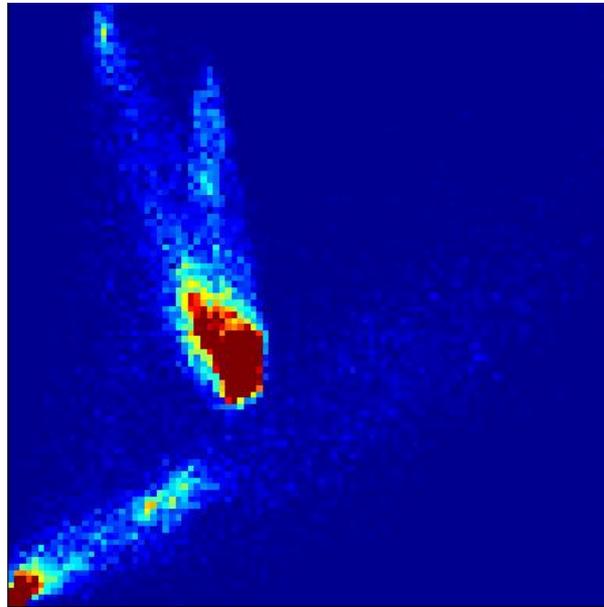
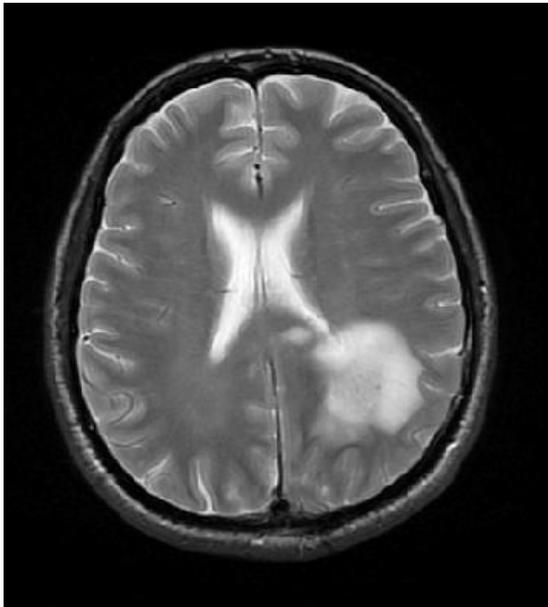




# Multi-modality image registration

Mutual information



**Now:**

## **Multi-modality image registration**

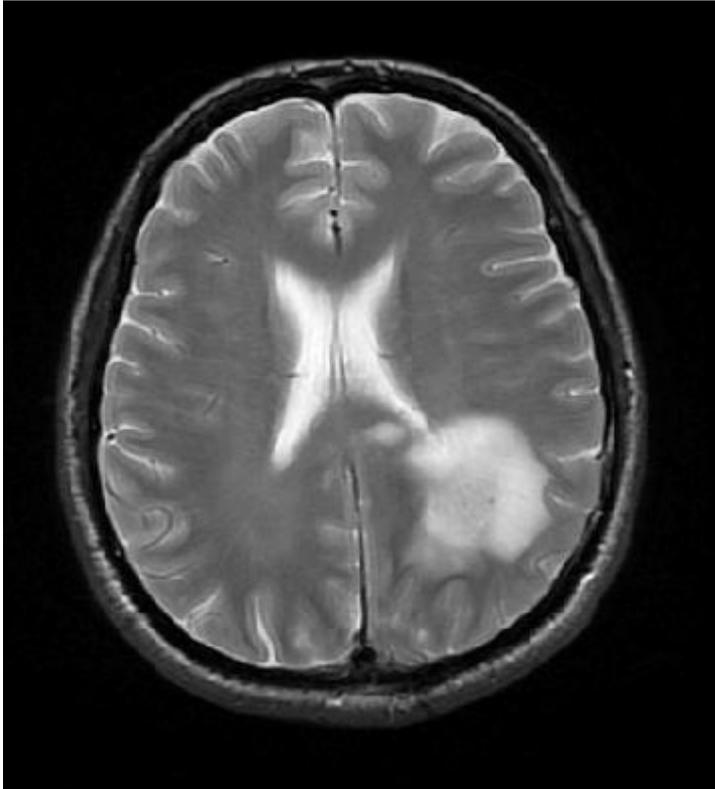
So far: Minimize the difference in pixel intensities

Problem: only works if both images are of the same type

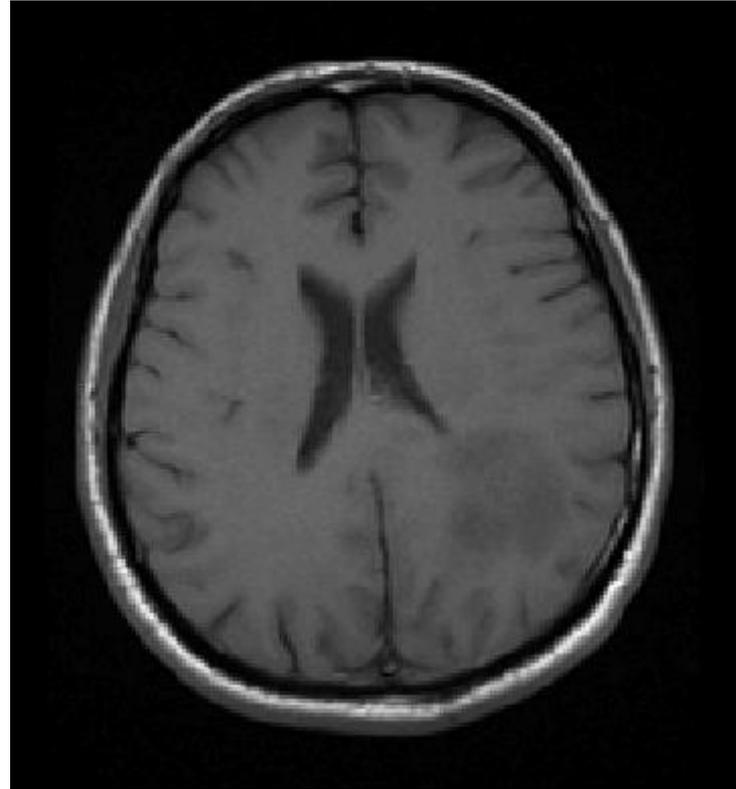
(CT is ideal – Hounsfield number is quantitative / scanner independent)

➔ Requires different cost function

# Example: T<sub>1</sub> / T<sub>2</sub> MR images

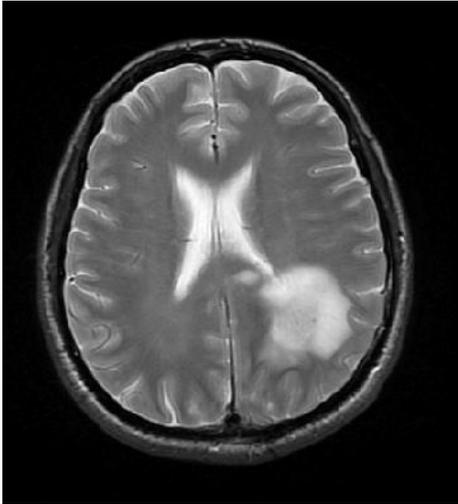


T2 image



T1 image

# Example: T<sub>1</sub> / T<sub>2</sub> MR images

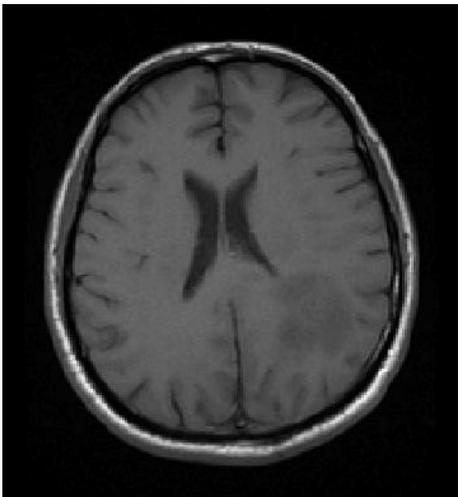


## **Intuition:**

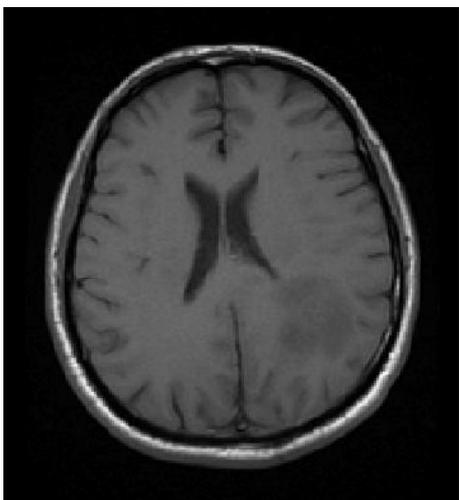
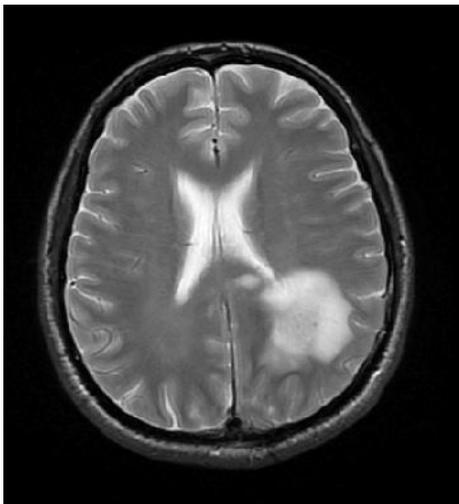
Regions with constant gray value in the image should be mapped to constant gray values in the reference image

## **Common approach:**

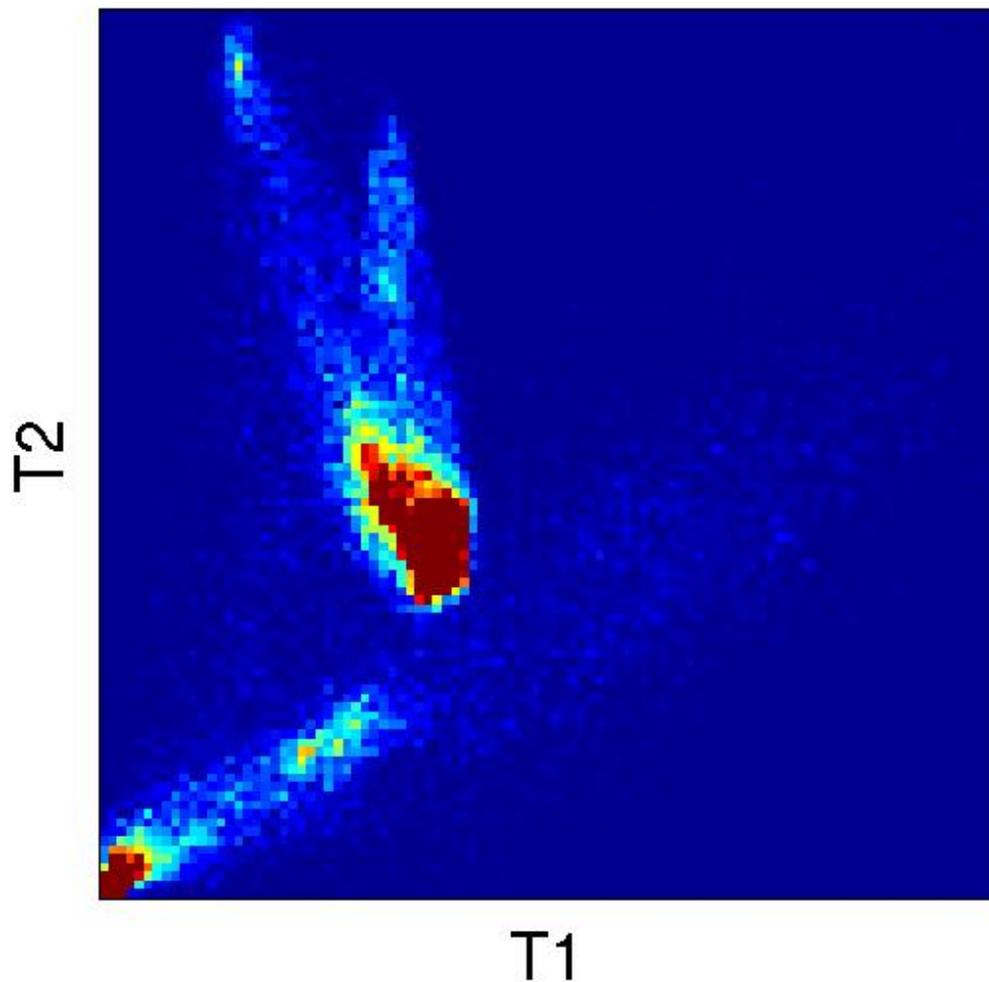
**Mutual information cost function**



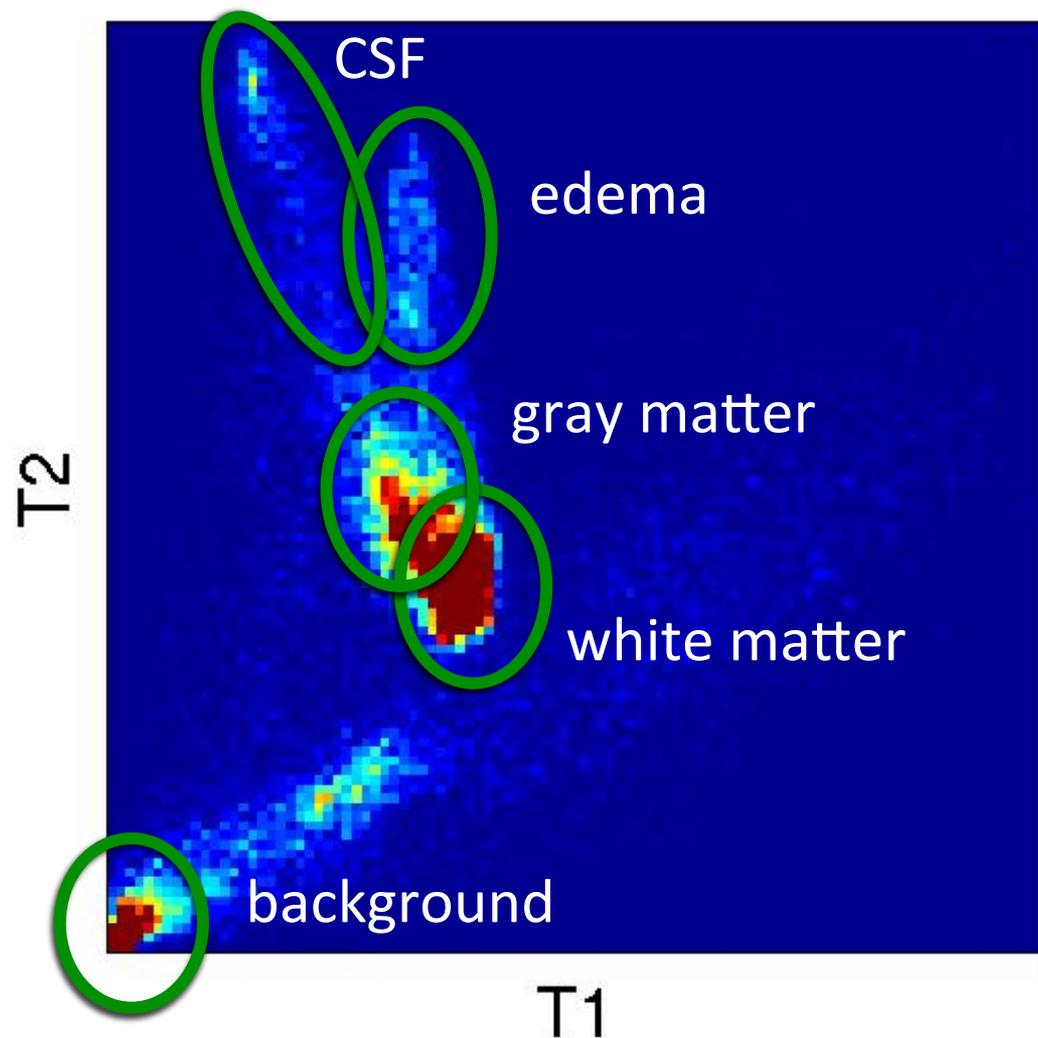
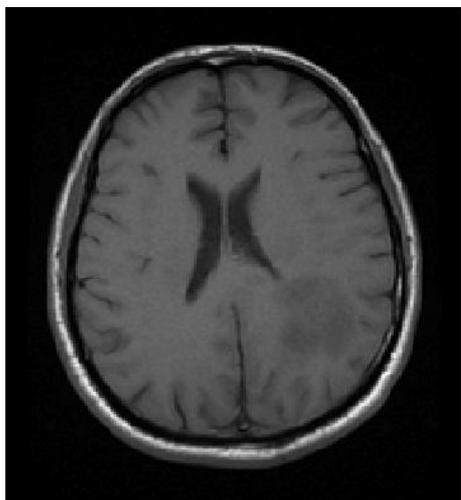
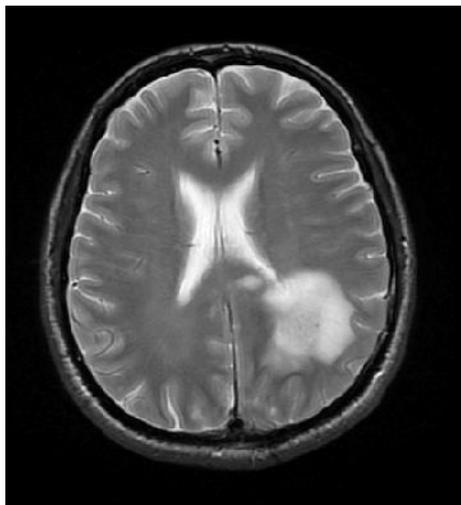
# Gray value correlation



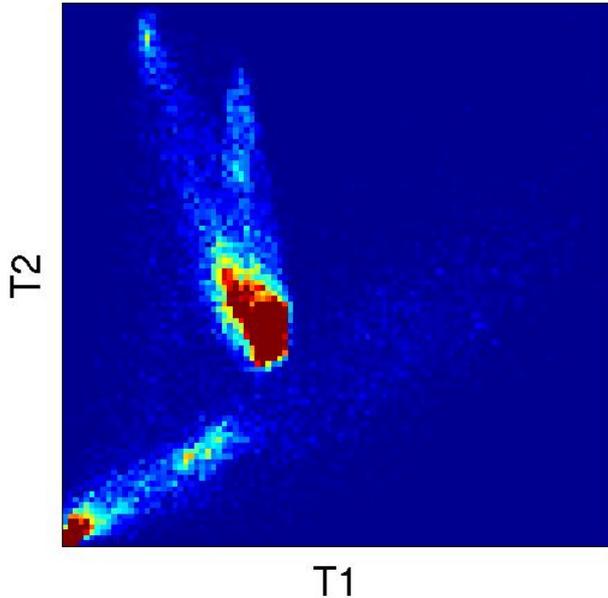
Joint gray value histogram of T1 and T2 image



# Gray value correlation



# Gray value correlation



## Idea:

If images are correctly registered, one can predict the gray value in the image by knowing the gray value in the reference image

This is quantified by the

## Mutual information

between the two gray value histograms

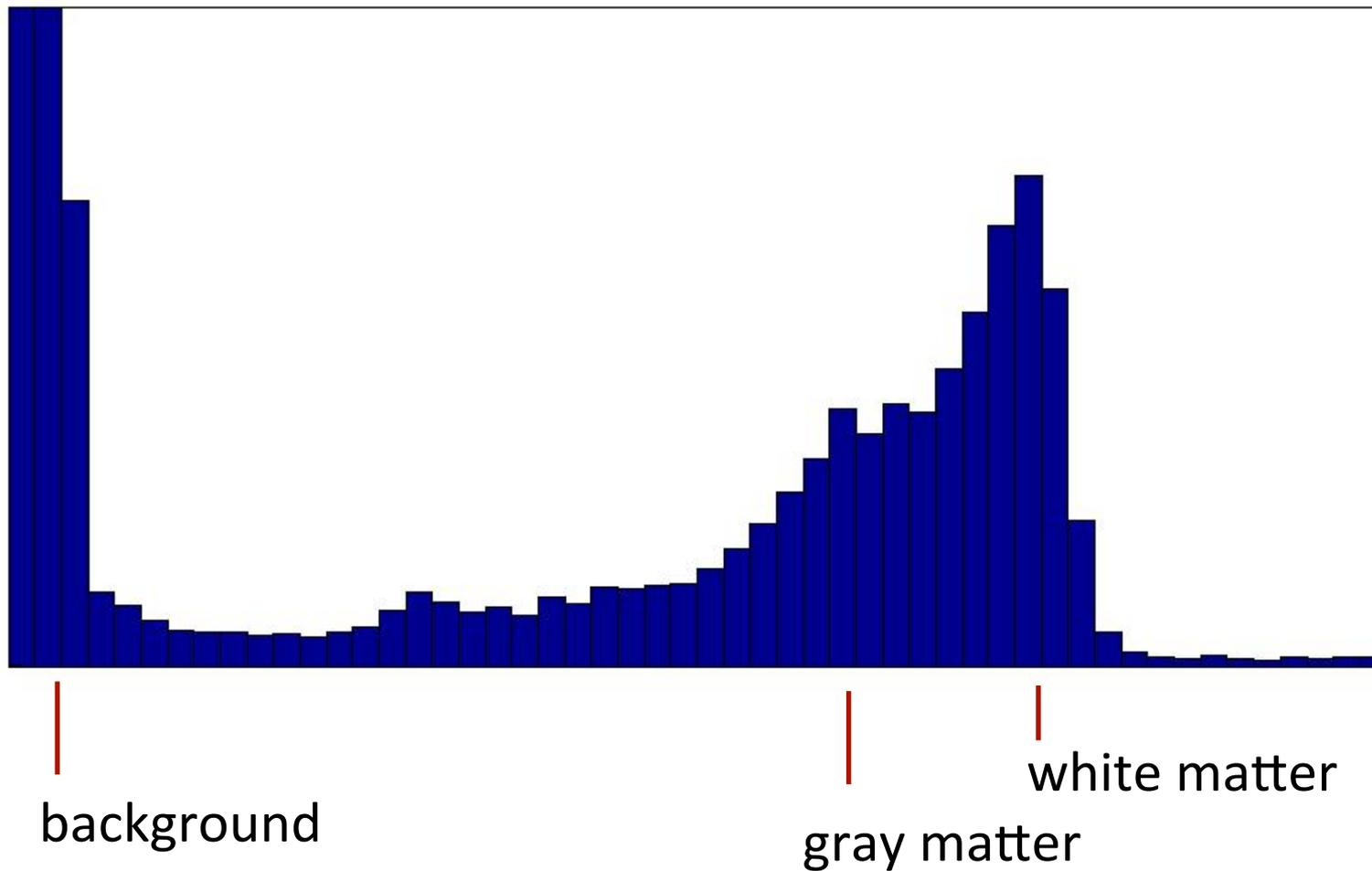
## Definition of Entropy (= Shannon Information)

$$H(A) = - \sum_n P(a_n) \log P(a_n)$$

random variable  $A$  with realizations  $a_n$

**Here:** “ $A$ ” corresponds to gray value of the image

## Histogram of T1 image



## Definition of Entropy

$$H(A) = - \sum_n P(a_n) \log P(a_n)$$

random variable  $A$  with realizations  $a_n$

**Here:** “ $A$ ” corresponds to gray value of in image voxel

**Entropy** = average information contained in one gray value  
(in “bit” if  $\log_2$  is used)

- Uniform image (peaked histogram) contains no information  $H(A) = 0$
- Uniform histogram has maximum entropy

# Conditional Entropy

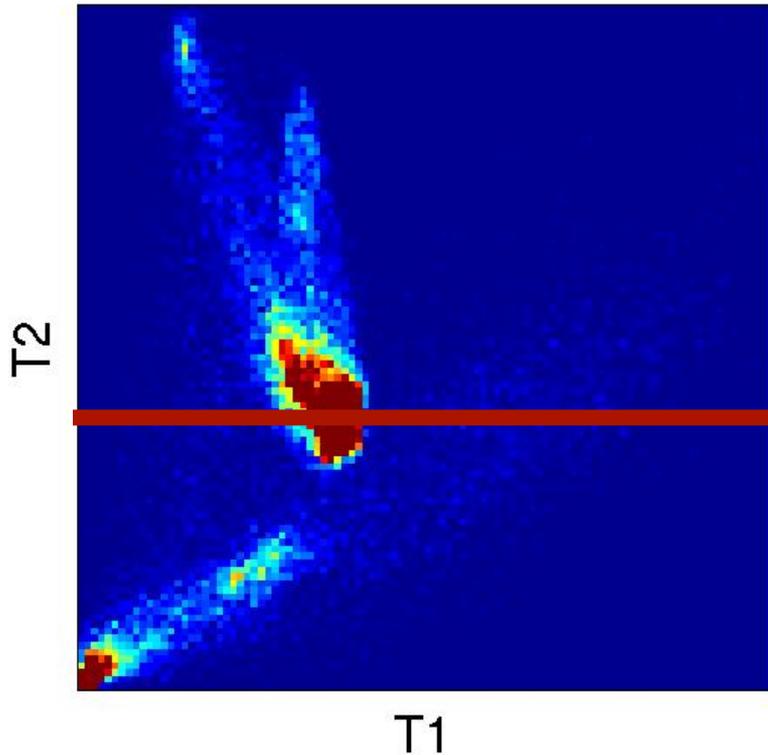
## Conditional Entropy

$$H(A|B) = \sum_m P(b_m) \left[ \underbrace{- \sum_n P(a_n | b_m) \log P(a_n | b_m)}_{\text{conditional probability}} \right]$$

$$H(A|B = b_m)$$

average information contained in a gray value in image A given that the gray value in image B is  $b_m$

# Gray value correlation



## Conditional Entropy:

$$H(A | B) \leq H(A)$$

knowing the gray value in image B reduces the average information contained in image A

(histogram becomes more peaked)

$$H(A | B) = H(A)$$

if and only if A and B are independent random variables

## Mutual information

$$MI(A, B) = H(A) - H(A | B)$$

**Mutual information  
of both histograms**

“how much information  
does the reference  
image contain over the  
image”

**Conditional entropy of image  
given the reference image**

“how undetermined is the gray  
value of the image after  
knowing the reference image”

**Entropy of image histogram A**

“how undetermined is the gray value of  
an image pixel”

## Mutual information

$$MI(A, B) = H(A) - H(A | B)$$

**Mutual information  
of both histograms**

**Conditional entropy of image  
given the reference image**

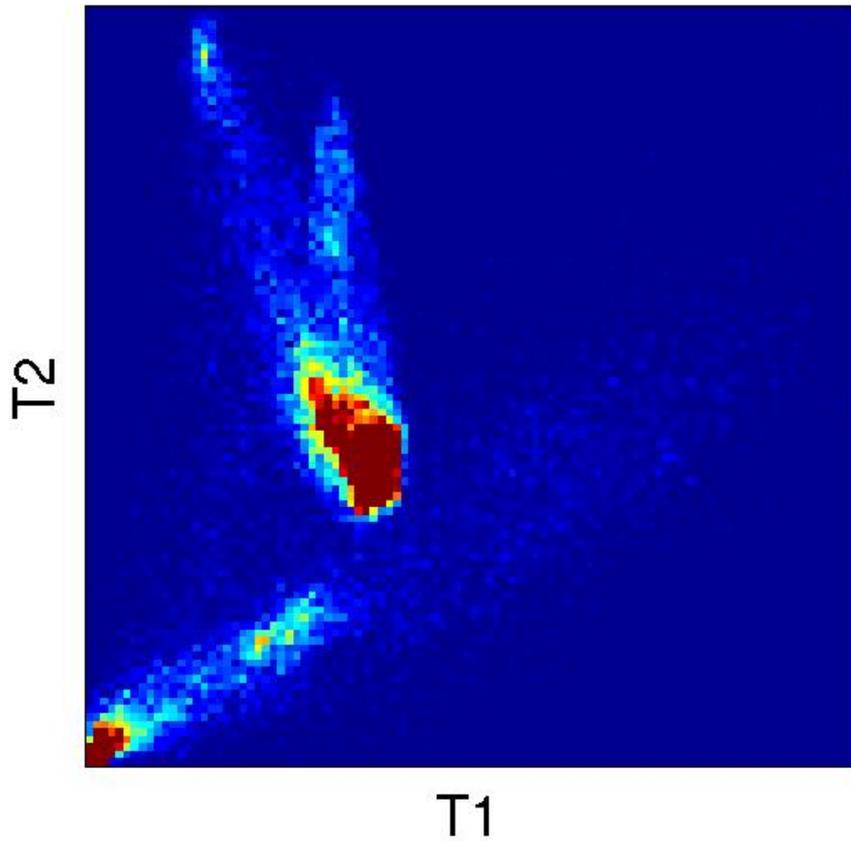
if histogram  $A|B$  is peaked, then  $H(A|B) \approx 0$

→  $MI(A, B) \approx H(A)$  is maximized

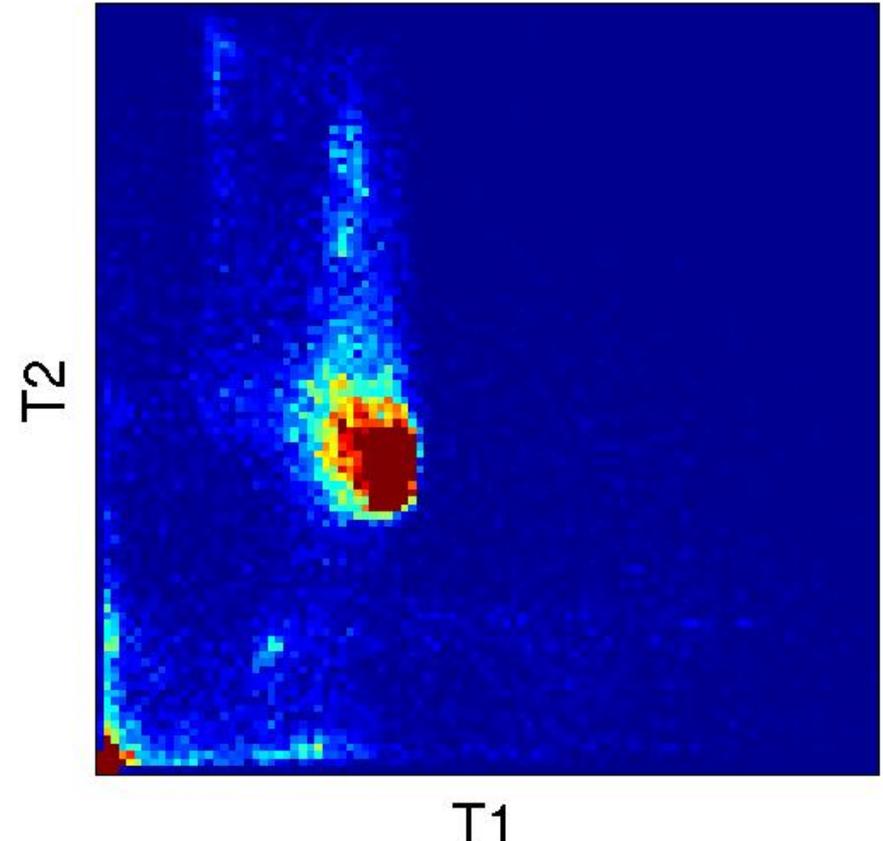
→ Image B contains as much information as possible about A

# Image misalignment

Gray value correlation is reduced if images are not registered



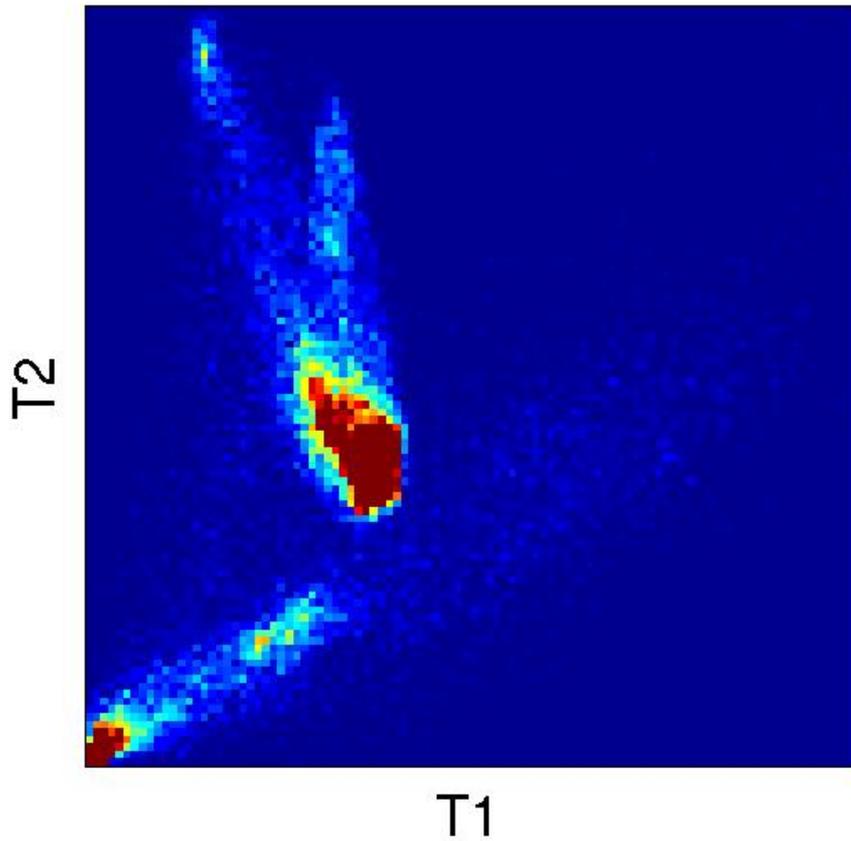
(registered)



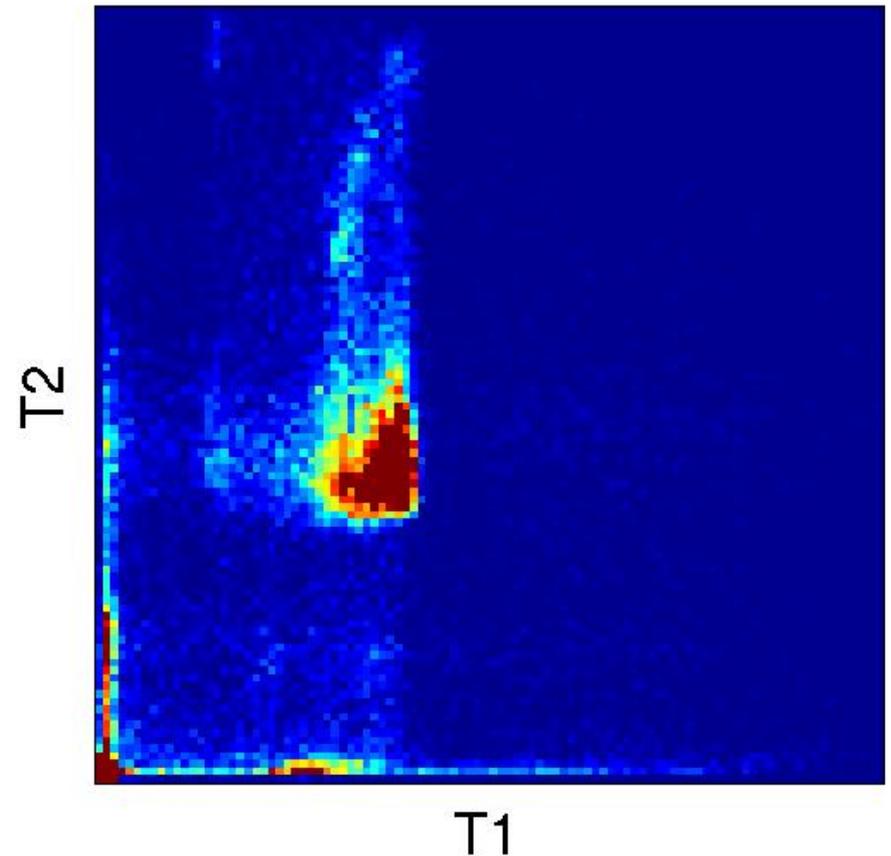
(shifted by 3 pixel (1.5 mm))

# Image misalignment

Gray value correlation is reduced if images are not registered



(registered)



(shifted by 10 pixel (5 mm))

# Registration using MI - interpretation

**Registration: Maximize mutual information**

$$MI(A, B) = H(A) - H(A | B)$$

**We are minimizing the entropy of the joint histogram**

**We are minimizing the conditional entropy of the transformed image given the reference image**

let's assume that's independent of the image transformation

## Express MI through joint histogram

$$\begin{aligned}MI(A, B) &= H(A) - H(A | B) \\ &= H(B) - H(B | A) \\ &= H(A) + H(B) - H(A, B)\end{aligned}$$

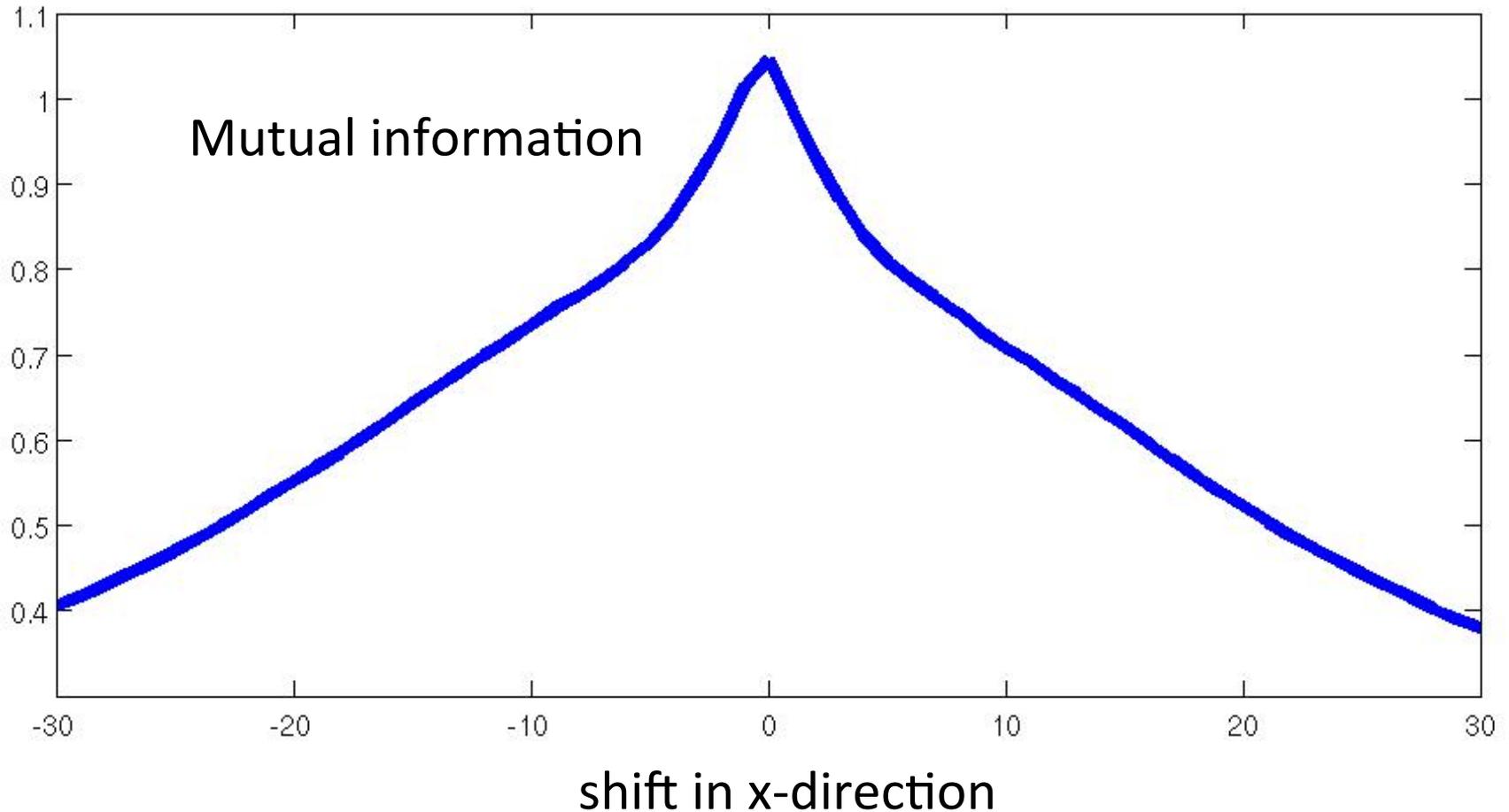
joint gray value histogram

$$MI(A, B) = \sum_{n,m} P(a_n, b_m) \log \left( \frac{P(a_n, b_m)}{P(a_n)P(b_m)} \right)$$

individual histograms

# Calculating gradients

**Mutual information (T1-T2) as a function of misalignment:**



## Maximizing the Mutual information cost function

$$MI\left(p_{mn}\left(I_R, I_T(\Theta)\right)\right) = \sum_{m,n} p_{mn} \log\left(\frac{p_{mn}}{p_m p_n}\right)$$

Mutual information depends on registration parameters through the transformed image and the joint histogram

# Calculating gradients

**Two options for gradient calculation:**

- 1. approximate gradients through finite differences**
- 2. calculate derivatives via the chain rule**

# Optimizing Mutual Information

## Gradient calculation:

$$\frac{\partial MI}{\partial \Theta_k} = \sum_{n,m} \frac{\partial MI}{\partial p_{nm}} \frac{\partial p_{nm}}{\partial \Theta_k}$$

Derivative of MI with respect to histogram bin (n,m)  
(can be calculated analytically)

How does the histogram depend on registration parameters

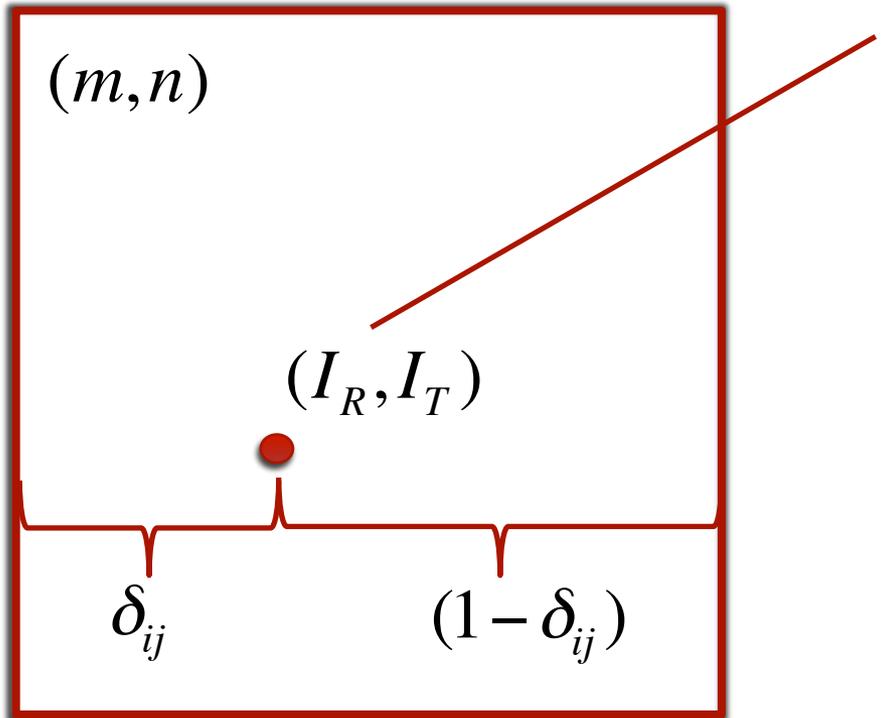
# Optimizing Mutual Information

$$\frac{\partial p_{nm}}{\partial \Theta_k} = \sum_{i,j} \left[ \underbrace{\frac{\partial p_{nm}}{\partial I} \Big|_{(x(i,j;\Theta), y(i,j;\Theta))}}_{\text{change of the joint histogram when changing the gray value in the transformed image (at the point that corresponds to voxel (i,j) )}} \underbrace{\frac{\partial I(x(i,j;\Theta), y(i,j;\Theta))}{\partial \Theta_k}}_{\text{see first lecture}} \right]$$

change of the joint histogram when changing the gray value in the transformed image (at the point that corresponds to voxel (i,j) )

sum over the contributions of all voxels to the joint histogram

# Gradient calculation



gray value pair of voxel  $(i,j)$

- Voxel  $(i,j)$  contributes to 4 histogram bins  
(weights determined by bilinear interpolation)
- changing the gray value changes the weightings of the 4 bins

$(m + 1, n + 1)$

4 adjacent histogram bins

## **Multi-modality registration requires different cost function**

Maximizing mutual information is popular choice

Advantage: no prior assumptions on gray value correlations needed

### **Assumption:**

When images are registered, the gray value in the reference image predicts the gray value in the image best

### **Gradient calculation:**

a bit messy