Image Reconstruction 1 – Planar reconstruction from projections

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1 Introduction

2 The 2D Radon transform
   - Projection

3 Inverting the 2D Radon transform
   - Backprojection
   - Central Slice theorem
   - The filtered backprojection (FBP) algorithm

4 Practical implementation
Invention of Computerized Tomography (CT)

Sir Godfrey N. Hounsfield
(Electrical Engineer)
EMI

Allan M. Cormack
(Physicist)
South Africa, Boston

Joint Nobel Prize for Physiology or Medicine, 1979
First CT scanner prototype (Hounsfield apparatus)
Outline

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2. The 2D Radon transform
   - Projection

3. Inverting the 2D Radon transform
   - Backprojection
   - Central Slice theorem
   - The filtered backprojection (FBP) algorithm

4. Practical implementation
Consider a function $f(x)$ of the variables $x = (x_1, x_2)$ in the plane $A$.

In CT, $f(x)$ stands for the distribution of attenuation coefficients in a planar cut through the patient’s body.

Let us assume that we know the “projections” (x-ray projections) of $f(x)$ for arbitrary projection angles.
From transmission to projection

\[ I = I_o e^{-\int_I ds} \]
Mathematically, the projection $\lambda$ is the integral of $f(x)$ along a (parallel) set of projection lines:

$$
\lambda_\phi(p) = \int_A f(x) \delta(p - x \cdot \hat{n}_\phi) \, d^2x
$$

Note: A projection line is described in the Hessian normal form by the equation $p = x \cdot \hat{n}_\phi$.

Note also: The $\delta$-function "picks" those points $x$ from the plane $A$ that lie on the projection line.
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Radon Transform

- We will consider all projections of $f$ as a two-dimensional function with the arguments $p$ and $\phi$, and write it as $\lambda(p, \phi)$. The transform $f(x_1, x_2) \rightarrow \lambda(p, \phi)$ is called a **Radon transform**\(^1\).

- In symbols:

$$\lambda(p, \phi) = \mathcal{R}\{f(x)\}.$$  

The problem of reconstructing $f(x)$ from the (known) projections $\lambda(p, \phi)$ is basically the determination of the inverse Radon transform, $\mathcal{R}^{-1}$.

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\(^1\)After the mathematician Johann Radon, who described the first mathematical method for a reconstruction from projections as early as in 1917.
The problem: inverting the Radon transform
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By backprojection we mean “smearing out” of the values of $\lambda_\phi(p)$ along the projection lines, over the plane $A$, which results in a streak image. Mathematically, backprojection under an angle $\phi$ is simply given by:

$$f_\phi(x) = \lambda_\phi(x \cdot \hat{n}_\phi).$$

If we perform backprojections for all angles within the interval $[0, \pi)$ and integrate the results, we get

$$f_b(x) = \int_0^\pi \lambda_\phi(x \cdot \hat{n}_\phi) \, d\phi.$$

$$f_b(x) = \mathcal{B} \{ \lambda(p, \phi) \} = \mathcal{B} \mathcal{R} \{ f(x) \}.$$
Backprojection
Backprojection alone does not reconstruct the object!

(a) Shepp and Logan phantom
(b) "Reconstruction" of (a) with backprojection
Backprojection alone does not reconstruct the object!
The **Central Slice Theorem** provides the relationship between the one-dimensional (1-D) FT of a projection $\lambda_\phi(p) = \mathcal{R}_\phi \{ f(x) \}$ and the 2-D FT of $f(x)$:

$$\Lambda_\phi(\nu) = \mathcal{F}_1 \{ \mathcal{R}_\phi \{ f(x) \} \}$$

$$= \int_{-\infty}^{\infty} \left[ \int_A f(x) \delta(p - x \cdot \hat{n}_\phi) \, d^2x \right] \exp(-2\pi i \nu p) \, dp$$

$$= \int_A f(x) \left[ \int_{-\infty}^{\infty} \delta(p - x \cdot \hat{n}_\phi) \exp(-2\pi i \nu p) \, dp \right] \, d^2x$$

$$= \int_A f(x) \exp(-2\pi i \nu x \cdot \hat{n}_\phi) \, d^2x.$$

The last integral is the 2-D Fourier transform $F(\rho)$ of the function $f(x)$ along the line $\rho = \nu \hat{n}_\phi$. 
Central Slice Theorem

Theorem (Central Slice Theorem)

The 1-D FT of the projection of a 2-D function yields the 2-D FT of the function along a line through the origin of the frequency domain.

Using operator notation we can write this as:

$$\mathcal{F}_1 \{ \mathcal{R}_\phi \{ f(x) \} \} (\nu) = \mathcal{F}_2 \{ f(x) \} (\rho = \nu \hat{n}_\phi)$$

or just

$$\mathcal{F}_1 \mathcal{R} = \mathcal{F}_2.$$
Central Slice Theorem

\[ x = (x_1, x_2) \]

\[ f(x) \]

\[ \rho = (\rho_1, \rho_2) \]

\[ \hat{n}_\phi \]

\[ \Lambda_\phi(v) \]

\[ \Lambda_\phi(p) \]

\[ \mathcal{R} \]

\[ \tilde{F}_1 \]

\[ \tilde{F}_2 \]

Image Reconstruction 1 – Planar reconstruction
Filtered Backprojection: formal derivation

Write $f(x)$ as the inverse Fourier transform of $F(\rho)$, in polar coordinates:

$$f(x) = \int_{-\infty}^{\infty} F(\rho) \exp(2\pi i \cdot x \cdot \rho) \, d^2\rho$$

$$= \int_{\nu=0}^{2\pi} \int_{\nu=0}^{\infty} \nu F(\nu \hat{n}_\phi) \exp(2\pi i \nu x \cdot \hat{n}_\phi) \, d\nu \, d\phi$$
Filtered Backprojection: formal derivation

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$$= \int_0^{2\pi} \int_0^\infty \nu F(\nu \hat{n}_\phi) \exp(2\pi i \nu x \cdot \hat{n}_\phi) \ d\nu \ d\phi$$

For symmetry reasons:

$$f(x) = \int_0^{2\pi} \int_0^\infty |\nu| F(\nu \hat{n}_\phi) \exp(2\pi i \nu x \cdot \hat{n}_\phi) \ d\nu \ d\phi$$
Filtered Backprojection: formal derivation

Write $f(x)$ as the inverse Fourier transform of $F(\rho)$, in polar coordinates:

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With the Central Slice Theorem we obtain finally:

$$f(x) = \int_{0}^{\infty} \int_{-\infty}^{\infty} |\nu| \Lambda_\phi(\nu) \exp(2\pi i \nu x \cdot \hat{n}_\phi) \, d\nu \, d\phi$$
Filtered Backprojection: algorithm

The function $f(x)$ can be reconstructed from the projection profiles $\lambda_\phi(p)$ using the following steps:

1. *Fourier transform* of $\lambda_\phi(p) \rightarrow \Lambda_\phi(\nu)$;
2. *multiplication* of $\Lambda_\phi(\nu)$ with $|\nu| \rightarrow \Lambda_\phi^*(\nu)$;
3. *inverse Fourier transform* of $\Lambda_\phi^*(\nu) \rightarrow \lambda_\phi^*(p')$;
4. *backprojection* of $\lambda_\phi^*(p')$ and integration over $\phi \rightarrow f(x)$.

The first three steps are a filtering (convolution) of the projection profiles with the filter $h^{-1}(p)$, which is the inverse FT of $H^{-1}(\nu) = |\nu|$.
Filtered Backprojection: intuitive explanation

1. Backprojection of $\lambda_\phi(p)$ under angle $\phi$ corresponds with creating a line through the origin of the 2D Fourier space.
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4. Can be corrected with $|\nu|$ filter.
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Discrete projection data (sinogram):

- We know $\lambda_m \cdot \Delta \phi (n \cdot \Delta p)$ for $n = -N, \ldots, N$, and $m = 1, \ldots, M$ with $M = \pi / \Delta \phi$.

- Assume that the sampling interval, $\Delta p$, satisfies the Nyquist sampling condition. This means, we assume that projection profiles in the Fourier domain, $\Lambda_{\phi}(\nu)$, are bandlimited within $-\frac{1}{2 \Delta p} < \nu < \frac{1}{2 \Delta p}$.

- Then the inverse transfer function $H^{-1}(\nu) = |\nu|$ can be restricted to the same interval, $\left[-\frac{1}{2 \Delta p}, \frac{1}{2 \Delta p}\right]$.

- The modified function

$$H^{-1}_r(\nu) = \begin{cases} |\nu| & \text{for } |\nu| \leq \frac{1}{2 \Delta p} \\ 0 & \text{otherwise} \end{cases}$$

is called “ramp filter”.
To determine the filter $h_r^{-1}(p)$ in the **spatial domain** we have to do an inverse Fourier transform of $H_r^{-1}(\nu)$ which yields:

$$h_r^{-1}(p) = F_1^{-1}\{H_r^{-1}(\nu)\} = \frac{1}{4\Delta p^2} \left(2 \text{sinc}\left(\frac{p}{\Delta p}\right) - \text{sinc}^2\left(\frac{p}{2\Delta p}\right)\right),$$

where \(\text{sinc}(x)\) stands for \(\sin(\pi x)/(\pi x)\).
To determine the filter $h_r^{-1}(p)$ in the **spatial domain** we have to do an inverse Fourier transform of $H_r^{-1}(\nu)$ which yields:

$$h_r^{-1}(p) = \mathcal{F}_1^{-1}\{H_r^{-1}(\nu)\}$$

$$= \frac{1}{4\Delta p^2} \left( 2 \operatorname{sinc}\left(\frac{p}{\Delta p}\right) - \operatorname{sinc}^2\left(\frac{p}{2\Delta p}\right) \right),$$

where $\operatorname{sinc}(x)$ stands for $\sin(\pi x)/(\pi x)$.

A sampling at discrete positions $p = n\Delta p$ yields the discrete version:

$$h_r^{-1}(n\Delta p) = \begin{cases} 
\frac{1}{4\Delta p^2} & \text{for } n = 0 \\
0 & \text{for } n \text{ even, } \neq 0 \\
-\frac{1}{n^2\pi^2\Delta p^2} & \text{for } n \text{ odd}.
\end{cases}$$

This filter goes back to Ramachandran and Lakshminarayanan. It is known as **“Ram-Lak”** filter.
Ram-Lak filter
Another commonly used filter is the so-called “Shepp and Logan” filter, which results from averaging (smoothing) of the Ram-Lak filter over intervals of the width $\Delta p$ (or in the frequency domain from the ramp filter $|\nu|$ by multiplication with $\text{sinc}(\nu \Delta p)$):

$$h_s^{-1}(p) = -\frac{2}{\pi^2 \Delta p^2} \frac{1 - 2(p/\Delta p) \sin(\pi p/\Delta p)}{4(p/\Delta p)^2 - 1}.$$  

The discrete version of this filter is very simple:

$$h_s^{-1}(n\Delta p) = -\frac{2}{\pi^2 \Delta p^2 (4n^2 - 1)}.$$
Shepp-Logan filter
Simple backprojection

Filtered backprojection
Homework 1: reconstruct yourself!

a) Take a picture of yourself and convert it to a grayscale 100 × 100 pixel square image.

b) Create your sinogram space for 100 projection angles.

c) Reconstruct your image by filtered backprojection using (i) the Ram-Lak filter, and (ii) the Shepp-Logan filter. Do the filtering in the spatial domain using filters \( h_r^{-1} \) (Ram-Lak) and \( h_s^{-1} \) (Shepp-Logan).
Further Reading


